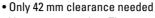
Rotary Measuring Technology Incremental hollow shaft encoder



Universal Type 5820





- Very easy mounting. The encoder is mounted directly on the drive shaft without couplings. This saves up to 30 % cost and 60 % clearance compared to shaft versions.
- Many variations
- Temperature and ageing compensation
- Short-circuit proof outputs
- Reverse connection protection for voltage supply

- RS 422 or push-pull output
- Resolution up to 5000 ppr
- Protection up to IP 66
- (Ex) available as explosion proof zone 2 and 22

Mechanical characteristics:

Speed without sealing:	max. 12000 min ⁻¹
Speed with sealing ¹⁾ :	max. 6000 min ⁻¹
Rotor moment of inertia:	approx. 6 x 10 ⁻⁶ kgm ²
Starting torque without sealing:	< 0.01 Nm
Starting torque with sealing:	< 0.05 Nm
Weight:	approx. 0.4 kg
Protection acc. to EN 60 529 without sealing:	IP 40
Protection acc. to EN 60 529 sealing:	IP 66
Working temperature without sealing:	-20° C up to +85 °C ²⁾³⁾
Working temperature with sealing:	-20° C up to +80 °C ²⁾³⁾
Operating temperature without sealing:	-20° C up to +90 °C ²⁾⁴⁾
Operating temperature with sealing:	-20° C up to +85 °C ²⁾⁴⁾
Shaft:	stainless steel H7
Shock resistance acc. to DIN-IEC 68-2-27	2000 m/s ² , 6 ms
Vibration resistance acc. to DIN-IEC 68-2-6:	100 m/s ² , 102000 Hz

Pulse rates available at short notice:

10, 20, 25, 30, 50, 60, 100, 120, 125, 127, 150, 180, 200, 216, 240, 250, 254, 256, 300, 314, 360, 375, 400, 500, 512, 600, 625, 720, 745, 750, 762, 800, 900, 927, 1000, 1024, 1250, 1270, 1400, 1500, 1800, 2000, 2048, 2250, 2400, 2500, 3000, 3600, 4000, 4096, 5000

Other pulse rates on request

Electrical characteristics:

Output circuit:	RS 422	RS 422	Push-pull	Push-pull	Push-Pull			
	(TTL-compatible)	(TTL-compatible)			(7272) ³⁾			
Supply voltage:	5 V (±5%) or	5 30 V DC	10 30 V DC	5 30 V DC	5 30 V DC			
	10 30 V DC							
Power consumption (no load)	-	-	typ. 55 mA /	typ. 55 mA /	-			
without inverted signal:			max. 125 mA	max. 125 mA	-			
Power consumption (no load)	typ. 70 mA/	typ. 70 mA/	typ. 80 mA/	typ. 80 mA/	50			
with inverted signals:	max. 90 mA	max. 90 mA	max.150 mA	max.150 mA	100			
Permissible load/channel:	max. ±20 mA	max. ±20 mA	max. ±30 mA	max. ±30 mA	max. ±20 mA			
Pulse frequency:	max. 300 kHz	max. 300 kHz	max. 300 kHz	max. 300 kHz	max. 300 kHz			
Signal level high:	min. 2.5 V	min. 2.5 V	min. UB-2.5 V	min. UB-1.5 V	min. Ub - 2.5 V			
Signal level low:	max. 0.5 V	max. 0.5 V	max. 2.0 V	max. 2.0 V	max. 0.5 V			
Rise time t _r	max. 200 ns	max. 200 ns	max. 1 µs	max. 1 µs	max. 1 µs			
Fall time t _f	max. 200 ns	max. 200 ns	max. 1 µs	max. 1 µs	max. 1 µs			
Short circuit proof outputs: ¹⁾ :	yes ²⁾	yes2)	yes	yes	yes			
Reverse connection protection at U _B :	5 V: no, 1	yes	yes	no	no			
	0 30 V: yes							
Conforms to CE requirements acc. to EN 61000-6-1, EN 61000-6-4 and EN 61000-6-3								

¹⁾ If supply voltage correctly applied

(If UB=5 V, short-circuit to channel, 0 V, or +UB is permitted)
(If UB=5-30 V, short-circuit to channel or 0 V is permitted)

3) Max. recommended cable length 30 \mbox{m}

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 $^{^{1)}}$ For continuous operation max. 3000 min $^{-1}$ ventilated

²⁾ Non-condensing

^{3) 70 °}C with Cable

^{4) 80 °}C with Cable

²⁾ Only one channel allowed to be shorted-out:

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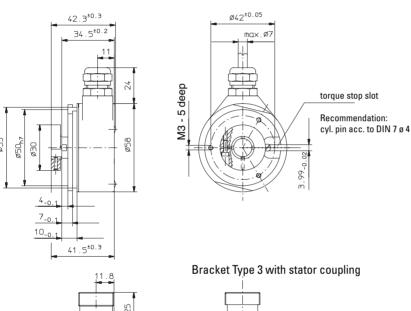
Terminal assignment

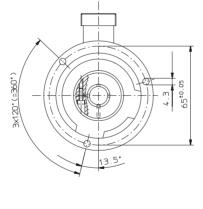
Sig.:	0 V	0 V	+U _B	+U _B	Α	Ā	В	B	0	0	<u></u>
		Sens ²⁾		Sens ²⁾							-
12 pin plug, Pin:	10	11	12	2	5	6	8	1	3	4	PH ¹⁾
Col.:	WH	GY PK	BN	BU RD	GN	YE	GY	PK	BU	RD	

¹⁾ PH = Shield is attached to connector housing

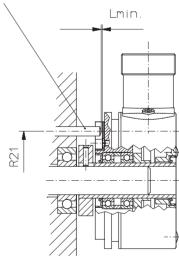
Dimensions

Bracket Type 1





Cyl. pin acc. to DIN 7 ø 4



Note: minimum insertion depth 1.5 x $D_{hollow shaft}$

45^{±0.3}

Mounting advice:

- The brackets and shafts of the encoder and drive should not both be rigidly coupled together at the same time.
- When mounting a hollow shaft encoder, we recommend using a torque stop pin that fits into the torque stop slot or a stator coupling.
- 3) When mounting the encoder ensure the dimension Lmin. is greater than the axial maximum play of the drive. Otherwise there is a danger that the device could mechanically seize up.

Sensor cables are connected to the supply voltage internally if long feeder cables are involved they can be used to adjust or control the voltage at the encoder

⁻ If sensor cables are not in use, they have to be insulated or 0 V $_{Sensor}$ has to be connected to 0 V and U $_{BSensor}$ has to be connected to U $_{R}$

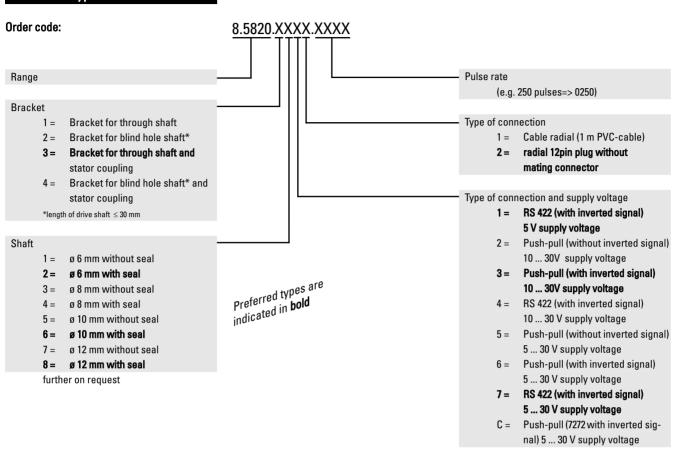
Using RS 422 outputs and long cable distances, a wave impedance has to be applied at each cable end.

Insulate unused outputs before initial startup.

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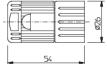


Accessories

Corresponding mating connector to Type of connection 2, 12 pin: Art.-No.. 8.0000.5012.0000 pin assignment cw
Corresponding mating connector with cable pre-assembled: Art.- No. 8.0000.6101.XXXX (XXXX = length [m])
Set includes Connector type 8.0000.5012.0000 and cable type 8.0000.6100.XXXX (Cable PUR 10 x 0.14 mm² + 2 x 0.5 mm²)

PIN allocation:





Dimensions:



Mounting kit for hollow shaft encoder ø 58 mm:

Various mounting variations can be supplied Delivery includes:

> 1 x parallel pin with thread Ord.-No. 8.0010.4700.0000 1 x mounting bracket Art.-no. T.035.009

Screw M3x5 Ord.-No. N.630.305

1 x long torque support slot

Ord.-No. T.051.672

Complete set: Ord.-No. 8.0010.4600.0000

Stator coupling two wings

For highly dynamic applications Includes:

1x coupling two wings

Express types 8.5820.X1XX.XXXX

8.5820.X3XX.XXXX

8.5820.X5XX.XXXX

8.5820.X7XX.XXXX

8.5820.XPXX.XXXX

8 5820 X2XX XXXX

8.5820.X4XX.XXXX

8.5820.X6XX.XXXX

8.5820.X8XX.XXXX

2x 2 screws

Complete set: Order-No.: 8.0010.4D00.0000 (see page 315)

Tether arm short

Order-No.: 8.0010.4R00.0000 (see page 316)

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