

Absolute Encoders – Multiturn

Standard SIL2/PLd, mech. Multiturn, optical	Sendix SIL 5863FS2 / 5883FS2 (Shaft / Hollow shaft)	SSI/BiSS-C+SinCos
Accessory safety technology		Order No.
Safety-M, basic modules	speed / position monitoring for 1 axis	8.MSP1.000
	speed / position monitoring for 2 axes (analogue inputs optional)	8.MSP2.XXX
Connection technology		
Connector, self-assembly (straight)	M23 female connector with coupling	8.0000.5012.0000
	M23 female connector with coupling, Ex zone 2/22	8.0000.5012.0000.Ex
Cordset, pre-assembled	M23 female connector with coupling nut, 2 m [2.19'] PVC cable	8.0000.6901.0002.0031

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories
 Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology
 You will find an overview of our systems and components for functional safety under www.kuebler.com/safety

Technical data

Notes regarding "Functional Safety"
These encoders are suitable for use in safety-related systems up to SIL2 acc. to EN 61800-5-2 and PLd to EN ISO 13849-1 in conjunction with controllers or evaluation units, which possess the necessary functionality. Additional functions can be found in the operating manual.

Safety characteristics	
Relevant standards	EN ISO 13849-1 / EN 61800-5-2, EN 61508
Classification	PLd / SIL2
System structure	2 channel (Cat. 3 / HFT = 1)
PFH_d value¹⁾	2.16 x 10 ⁻⁸ h ⁻¹
Proof-test interval	20 years

Mechanical characteristics	
Max. speed, shaft version	
up to 70°C [158°F]	12 000 min ⁻¹ , 10 000 min ⁻¹ (continuous)
up to T _{max}	8 000 min ⁻¹ , 5 000 min ⁻¹ (continuous)
Max. speed, hollow shaft version	
up to 70°C [158°F]	9 000 min ⁻¹ , 6 000 min ⁻¹ (continuous)
up to T _{max}	6 000 min ⁻¹ , 3 000 min ⁻¹ (continuous)
Starting torque - at 20°C [68°F]	
shaft version	< 0.01 Nm
hollow shaft version	< 0.03 Nm
Moment of inertia	
shaft version	4.0 x 10 ⁻⁶ kgm ²
hollow shaft version	7.0 x 10 ⁻⁶ kgm ²
Load capacity of shaft	
radial	80 N
axial	40 N
Weight	approx. 0.45 kg [15.87 oz]
Protection acc. to EN 60529	
housing side	IP67
shaft side	IP65
Hazardous area approval	optional zone 2 and 22
Working temperature range	
	-40°C ... +90°C ²⁾ [-40°F ... +194°F] ²⁾
Material	
shaft / hollow shaft	stainless steel
flange	aluminium
housing	zinc die-cast housing
cable	PVC
Shock resistance acc. EN 60068-2-27	500 m/s ² , 11 ms
Vibration resistance acc. EN 60068-2-6	200 m/s ² , 10 ... 150 Hz

Electrical characteristics	
Power supply	5 V DC ± 5% or 10 ... 30 V DC
Current consumption	
5 V DC	max. 80 mA
(no output load) 10 ... 30 V DC	max. 50 mA
Reverse polarity protection of the power supply (+V)	yes
Short circuit proof outputs	yes ³⁾
UL approval	File 224618
CE compliant acc. to	EMC guideline 2004/108/EC Machinery directive 2006/42/EC
RoHS compliant acc. to	guideline 2002/95/EC

- The specified value is based on a diagnostic coverage of 90%, that must be achieved with an encoder evaluation unit.
The encoder evaluation unit must meet at least the requirements for SIL2.
- Cable version: -30 °C ... +90 °C [-22 °F ... +194 °F]
- Short circuit to 0 V or to output, one channel at a time, power supply correctly applied

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SSI/BiSS-C + SinCos

SSI interface	
Output driver	RS485 transceiver type
Permissible load / channel	max. ±20 mA
Signal level	HIGH typ 3.8 V LOW at I _{Load} = 20 mA typ 1.3 V
Singleturn resolution	10 ... 14 bit and 17 bit ¹⁾
Number of revolutions	4096 (12 bit)
Code	Binary or Gray
SSI clock rate	resolution ST ≤ 14 bit 50 kHz ... 2 MHz resolution ST ≥ 15 bit 50 kHz ... 125 kHz
Monoflop time	≤ 15 µs
Note: If the clock starts cycling within the monoflop time, a second data transfer starts with the same data. If the clock starts cycling after the monoflop time, the data transfer starts with the new values. The update rate is dependent on the clock speed, data length and monoflop-time.	
Data refresh rate	resolution ST ≤ 14 bit ≤ 1 µs resolution ST ≥ 15 bit 4 µs
Status and parity bit	on request

BiSS-C interface	
Singleturn resolution	10 ... 14 bit and 17 bit ¹⁾
Number of revolutions	4096 (12 bit)
Code	Binary
Clock rate	up to 10 MHz
Max. update rate	< 10 µs, depends on the clock rate and the data length
Data refresh rate	≤ 1 µs
Note:	<ul style="list-style-type: none"> – Bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings – CRC data verification

SinCos interface	
Max. frequency -3dB	400 kHz
Signal level	1 V _{pp} (± 10%)
Short circuit proof	yes
Pulse rate	2048 ppr

SET input or SET button	
Input	active HIGH
Input type	comparator
Signal level	HIGH min: 60 % of +V, max: +V LOW max: 25 % of +V (power supply)
Input current	< 0.5 mA
Min. pulse duration (SET)	10 ms
Timeout after SET signal	14 ms
Reaction time (DIR input)	1 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input or by pressing the optional SET button (with a pencil, ball-point pen or similar). Other preset values can be factory-programmed. The SET input has a signal delay time of approx. 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approx. 15 ms before the new position data can be read. During this time the LED is ON.

DIR input	
A HIGH signal switches the direction of rotation from the default CW to CCW. This function can also be factory-programmed to be inverted. If DIR is changed when the device is already switched on, then this will be interpreted as an error. The LED will come ON and the status output will switch to LOW.	

Power-on delay	
After Power-ON the encoder requires a time of approx. 150 ms before valid data can be read.	

LED	
The optional LED (red) serves to display various alarm or error messages. In normal operation the LED is OFF.	
If the LED is ON (status output LOW) this indicates:	
<ul style="list-style-type: none"> - Sensor error, singleturn or multiturn (soiling, glass breakage etc.) - LED error, failure or ageing - Over- or under-temperature 	
In the SSI mode, the fault indication can only be reset by switching off the power supply to the device.	

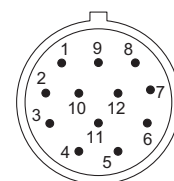
Terminal assignment

Interface	Type of connection	Cable (isolate unused wires individually before initial start-up)													
		Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	\bar{A}	B	\bar{B}	\perp
3, 4	1, 2, E	Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield

Interface	Type of connection	M23 connector, 12-pin													
		Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	\bar{A}	B	\bar{B}	\perp
3, 4	3, 4	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH

- +V: Encoder power supply +V DC
- 0 V: Encoder power supply ground GND (0 V)
- C+, C-: Clock signal
- D+, D-: Data signal
- SET: Set input. The current position becomes defined as position zero.
- DIR: Direction input: If this input is active, output values are counted backwards (decrease) when the shaft is turning clockwise.
- A, \bar{A} : cosine signal
- B, \bar{B} : sine signal
- PH \perp : Plug connector housing (shield)

Top view of mating side, male contact base



M23 connector, 12-pin

¹⁾ Other options on request

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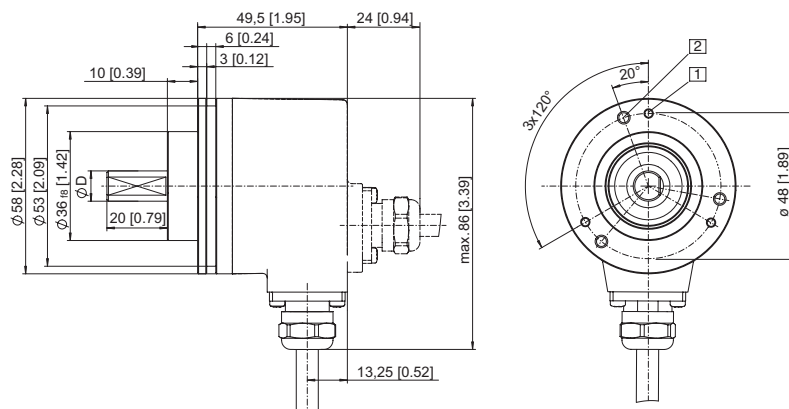
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Dimensions shaft version

Dimensions in mm [inch]

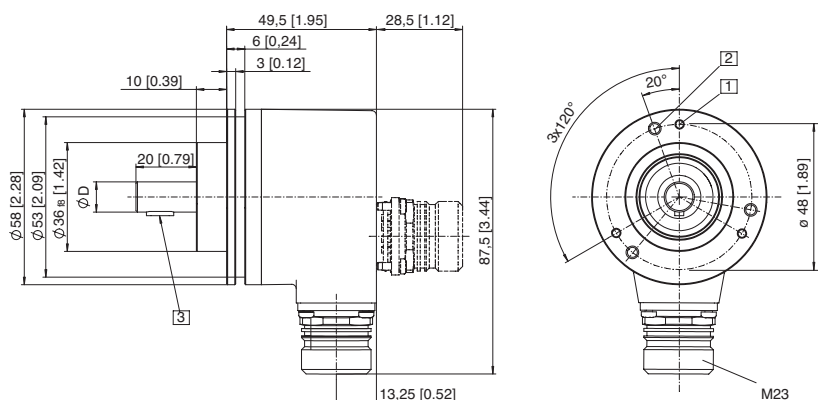
Clamping flange, \varnothing 58 [2.28] Flange type 1 with shaft type 2 (Drawing with cable)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep
- D = 10 ^{H7} [0.39]



Clamping flange, \varnothing 58 [2.28] Flange type 1 with shaft type A (Drawing with M23 connector)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep
- 3 Feather key DIN 6885 - A - 3x3x6
- D = 10 ^{H7} [0.39]



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Dimensions hollow shaft version

Dimensions in mm [inch]

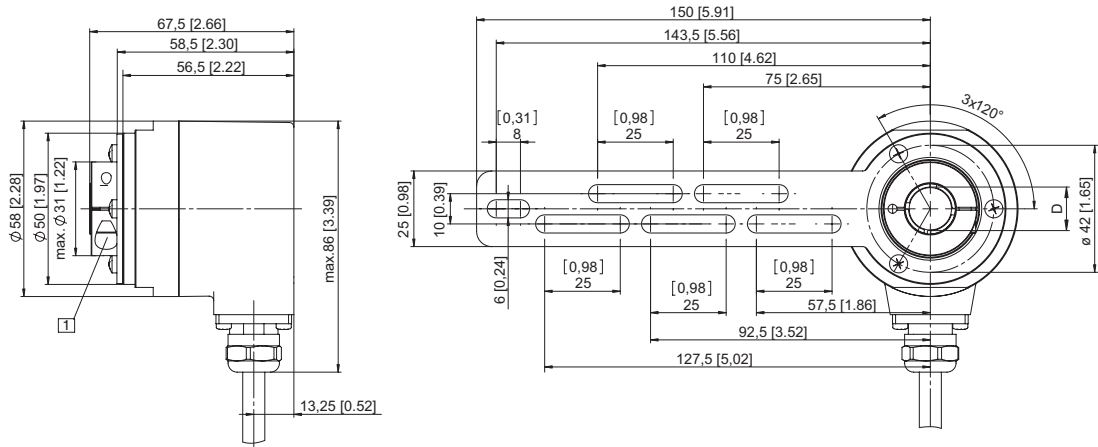
Flange with torque stop set

Flange type A

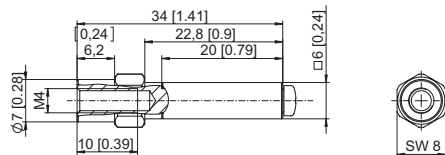
(Drawing with cable)

- 1 SW 3, recommended torque for the clamping ring 2.5 Nm

D = \varnothing 10^{H7} [0.39]
 \varnothing 12^{H7} [0.47]
 \varnothing 14^{H7} [0.55]



Torque pin with rectangular sleeve with M4 thread, 10 [0.39] deep



Flange with stator coupling, \varnothing 63 [2.48] and hollow shaft

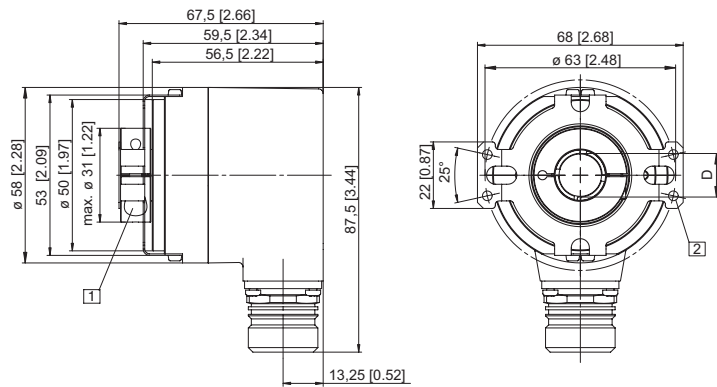
Flange type B

(Drawing with M23 connector)

- 1 SW 3, recommended torque for the clamping ring 2.5 Nm

- 2 for (4x) M3 screw

D = \varnothing 10^{H7} [0.39]
 \varnothing 12^{H7} [0.47]
 \varnothing 14^{H7} [0.55]



Flange with stator coupling, \varnothing 63 [2.48] and tapered shaft

Flange type B

(Drawing with tangential cable outlet)

- 1 for (4x) M3 screw

- 2 Status LED

- 3 SET button

- 4 SW 4

